Special Boundary Approximation Methods for Laplace Equation Problems with Boundary Singularities

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Abstract

We investigate the convergence of special boundary approximation methods (BAMs) used for the solution of Laplace problems with a boundary singularity. In these methods, the solution is approximated in terms of the leading terms of the asymptotic solution around the singularity. Since the approximation of the solution satisfies identically the governing equation and the boundary conditions along the segments causing the singularity, only the boundary conditions along the rest of the boundary need to be enforced. Four methods of imposing the essential boundary conditions are considered: the Penalty, Hybrid and Penalty/Hybrid BAMs and the BAM with Lagrange multipliers. A priori error analyses and numerical experiments are carried out for the case of the Motz problem, and comparisons between all methods are made.

Key words: Elliptic equation, boundary singularity, Motz problem, boundary approximation methods, penalty method, hybrid method, Lagrange multipliers, singular coefficients, error estimates, convergence

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1 Introduction

As in Li [9], we employ the term *Boundary Approximation Method* (BAM) for numerical methods used for the solution of boundary value problems when the solution is approximated over the entire domain as a linear combination of certain particular solutions of the governing equation. Since the governing equation is identically satisfied, only the enforcement of the boundary conditions is necessary in order to obtain the unknown coefficients of the above linear combination. BAMs include the Boundary Element Method [3] and the Method of Fundamental Solutions [7], in which the approximate solution is expressed in terms of fundamental solutions of the governing equation. The main advantage of the BAMs is that the dimension of the problem is reduced by one, which implies that the required computational cost is considerably reduced.

Special BAMs can be developed in the case of elliptic boundary value problems with a boundary singularity. If the local asymptotic solution around the singularity is known and converges over the entire solution domain, then the leading terms of the solution expansion can be used for the approximation of the solution. The additional advantages of such special BAMs are the following:

(a) Since the boundary conditions along the boundary parts causing the singularity are identically satisfied, application of the boundary conditions is necessary only along the remaining parts of the boundary.

(b) The singular coefficients, i.e. the leading coefficients of the asymptotic solution expansion, are calculated directly.

(c) The accuracy and the rate of convergence are considerably improved, compared to those of standard numerical methods which are seriously affected by the presence of singularities [4], [6], [9].

The approximation of the solution with the leading terms of the local asymptotic expansion may be employed only locally, i.e. in a subdomain $\Omega_1$ containing the singularity. Such an approach is mandatory if the domain of convergence of the asymptotic solution is a subset of the domain $\Omega$ (which should be a superset of $\Omega_1$). One may then use another set of particular solutions or employ standard numerical methods in order to approximate the solution and apply the boundary conditions in the remaining part $\Omega_2$ of the domain ($\Omega = \Omega_1 \cup \Omega_2$). Obviously, in the latter case, the method is not a BAM. A difficulty associated with this approach comes from the need of imposing proper coupling conditions along the interface of $\Omega_1$ and $\Omega_2$ (see, e.g., [8]). Li [9] considered a benchmark Laplace equation problem with a boundary singularity, known as the Motz problem, and investigated different coupling techniques when finite elements, finite differences, and the finite volume method are employed over $\Omega_2$. 

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What distinguishes the various special BAMs used for solving elliptic boundary value problems with a boundary singularity is the way the essential boundary conditions are enforced. Li et al. [8] and Arad et al. [1] employed least-squares techniques, whereas Georgiou and co-workers [4]–[6] employed Lagrange multipliers. Li [9] also considered other techniques, such as the Penalty method, the Hybrid method and the Penalty/Hybrid method which can be viewed as a combination of the former two methods.

The objective of the present work is to carry out a priori error analyses for various special BAMs which will allow the optimal choice of the parameters involved, leading to exponential convergence rates. For demonstration purposes, we have chosen to study the Motz problem [12].

In Section 2, we consider a general Laplace equation problem with Dirichlet and mixed boundary conditions and formulate the corresponding Galerkin and minimization problems with the Penalty, the Hybrid and the Penalty/Hybrid BAMs. For comparison purposes, the BAM with Lagrange multipliers [4], [6] is also considered. In Section 3, the application of the above four methods to the Motz problem is demonstrated, and in Sections 4–7 the corresponding error analyses are presented. Finally, in Section 8, we present some representative numerical experiments validating the error analyses, and make comparisons between all BAMs under study.

2 Formulations for the Laplace equation

For simplicity, we present the formulations of the BAMs for the special case of the Laplace equation. These formulations are easily extended to more general elliptic problems; see, e.g., [9]. We consider the Laplace equation in a plane, simply connected polygonal domain $\Omega$,

$$
\Delta u = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0 \quad \text{in} \quad \Omega \tag{2.1}
$$

with mixed boundary conditions:

$$
u = g_1 \quad \text{on} \quad \Gamma_1 \tag{2.2}$$

$$\frac{\partial u}{\partial n} + q u = g_2 \quad \text{on} \quad \Gamma_2 \tag{2.3}
$$

where $\Gamma_1 \cup \Gamma_2 = \partial \Omega$, $|\Gamma_1| > 0$, the functions $g_1, g_2$ and $q$ are sufficiently smooth, $q|_{\Gamma_2} \geq 0$, and $n$ is the outward normal direction to the boundary.
2.1 Weak formulations and Lagrange multipliers

Before proceeding to the various descriptions of the BAMs it is instructive to present first the standard weak formulations of the problem (2.1)–(2.3), i.e. the Galerkin weak form and its equivalent variational formulation, and discuss briefly the use of Lagrange multipliers for the enforcement of the essential boundary condition (2.2) on $\Gamma_1$. Let us employ the following notation for the Sobolev spaces of interest:

$$H^1(\Omega) = \{ v : v, v_x, v_y \in L^2(\Omega) \} ,$$

(2.4)

$$H^1_0(\Omega) = \{ v : v, v_x, v_y \in L^2(\Omega), \ v|_{\Gamma_1} = 0 \} .$$

(2.5)

We are also interested in the following subset of $H^1(\Omega)$:

$$H^1_*(\Omega) = \{ v : v, v_x, v_y \in L^2(\Omega), \ v|_{\Gamma_1} = g_1 \} .$$

(2.6)

In the Galerkin method, a solution $u \in H^1_*(\Omega)$ is sought such that

$$B(u, v) = F(v), \ \forall \ v \in H^1_0(\Omega)$$

(2.7)

where

$$B(u, v) = \iint_{\Omega} \nabla u \cdot \nabla v \, ds + \int_{\Gamma_2} q \, uv \, d\ell$$

(2.8)

and

$$F(v) = \int_{\Gamma_2} g_2 v \, d\ell .$$

(2.9)

The solution $u$ of the Galerkin problem (2.7) minimizes the quadratic functional

$$I(v) = \frac{1}{2} B(v,v) - F(v), \ v \in H^1_*(\Omega)$$

(2.10)

or

$$I(v) = \frac{1}{2} \iint_{\Omega} |\nabla v|^2 \, ds + \frac{1}{2} \int_{\Gamma_2} q \, v^2 \, d\ell - \int_{\Gamma_2} g_2 v \, d\ell , \ v \in H^1_*(\Omega) .$$

(2.11)
Thus the equivalent minimization problem is to find \( u \in H^1_*(\Omega) \) such that

\[
I(u) = \min_{v \in H^1_*(\Omega)} I(v) .
\] (2.12)

If now, the essential boundary condition (2.2) on \( \Gamma_1 \) is enforced by means of Lagrange multipliers \( \lambda = \partial u / \partial n \big|_{\Gamma_1} \), then the weak form of the problem (2.1)–(2.3) becomes [2]: Find \((u, \lambda) \in H^1(\Omega) \times H^{-1/2}(\Gamma_1)\) such that

\[
B(u, v) + G(u, v; \lambda, \mu) = F(v) \quad \forall (v, \mu) \in H^1(\Omega) \times H^{-1/2}(\Gamma_1),
\] (2.13)

where \( B(\cdot, \cdot) \) and \( F(\cdot) \) are given by (2.8) and (2.9), respectively, and

\[
G(u, v; \lambda, \mu) = - \int_{\Gamma_1} (\lambda v + \mu (u - g_1)) dl.
\] (2.14)

Here \( H^{-1/2}(\Gamma_1) \) is the dual space of \( H^{1/2}(\Gamma_1) \). If

\[
H^{1/2}(\partial \Omega) = \left\{ u \in H^1(\Omega) : u|_{\partial \Omega} \in L^2(\Omega) \right\}
\] (2.15)

is the trace space of functions in \( H^1(\Omega) \), \( T \) denotes the trace operator, and the norm of \( H^{1/2}(\partial \Omega) \) is defined as

\[
\| \psi \|_{1/2, \partial \Omega} = \inf_{u \in H^1(\Omega)} \left\{ \| u \|_{1, \Omega} : Tu = \psi \right\},
\] (2.16)

then \( H^{-1/2}(\partial \Omega) \) is defined as the closure of \( H^0(\partial \Omega) \equiv L^2(\partial \Omega) \) with respect to the norm

\[
\| \varphi \|_{-1/2, \partial \Omega} = \sup_{\psi \in H^{1/2}(\partial \Omega)} \frac{\int_{\partial \Omega} \varphi \psi}{\| \psi \|_{1/2, \partial \Omega}}.
\] (2.17)

The reader is referred to [2] or [16] for more details.

It is clear that the Galerkin problem (2.13) takes the form

\[
\iint_{\Omega} \nabla u \cdot \nabla v ds + \int_{\Gamma_2} quvd\ell - \int_{\Gamma_1} (\lambda v + \mu u)d\ell = \int_{\Gamma_2} g_2vd\ell - \int_{\Gamma_1} g_1ud\ell.
\] (2.18)
Its solution $(u, \lambda) \in H^1(\Omega) \times H^{-1/2}(\Gamma_1)$ creates a stationary point for the (not positive definite) functional

$$I(v, \lambda) = \frac{1}{2} \int_{\Omega} (\nabla v)^2 \, ds + \frac{1}{2} \int_{\Gamma_2} q v^2 \, d\ell - \int_{\Gamma_2} g_2 v \, d\ell - \int_{\Gamma_1} \lambda (v - g_1) \, d\ell.$$  \hspace{1cm} (2.19)

Note that the Lagrange multiplier function $\lambda = \partial u / \partial n |_{\Gamma_1}$ is treated as an additional unknown variable.

### 2.2 Boundary Approximation Methods

The basic characteristic of the boundary approximation methods is that the solution of the problem (2.1)–(2.3) is sought in a finite dimensional subspace

$$V_N = \text{span} \{ \Phi_i \}_{i=1}^N,$$ \hspace{1cm} (2.20)

where $\{ \Phi_i \}_{i=1}^N$ is a finite set of analytic, linearly independent basis functions, satisfying

$$\Delta \Phi_i = 0 \quad \text{in} \quad \Omega, \; i = 1, \ldots, N.$$ \hspace{1cm} (2.21)

Thus the approximate solution $u_N \in V_N$ is of the form

$$u_N = \sum_{i=1}^N a_i^N \Phi_i,$$ \hspace{1cm} (2.22)

where $a_i^N, \; i = 1, \ldots, N$, are unknown coefficients to be determined. The admissible functions $v$ also belong to $V_N$ and do not necessarily satisfy the essential boundary condition on $\Gamma_1$. Due to (2.21), any function $v \in V_N$ satisfies the Laplace equation. Therefore, the double integrals in the Galerkin problems (2.7) or (2.18) and in the functionals (2.11) or (2.19) are reduced to boundary integrals:

$$\int_{\Omega} \nabla u \cdot \nabla v \, ds = \int_{\partial \Omega} u \frac{\partial v}{\partial n} \, d\ell \quad \text{and} \quad \int_{\Omega} (\nabla v)^2 \, ds = \int_{\partial \Omega} v \frac{\partial v}{\partial n} \, d\ell.$$  \hspace{1cm} (2.23)

The essential boundary condition on $\Gamma_1$ can be enforced using different techniques [9]. The variational formulations for the Penalty, the Hybrid and the
Penalty/Hybrid BAMs are conveniently combined by introducing the parameters $w \geq 0$ and $\alpha \in [0,1]$. An approximate solution $u_N \in V_N$ is sought such that

\[ I(u_N) = \min_{v \in V_N(\Omega)} I(v) \tag{2.23} \]

where

\[ I(v) = \frac{1}{2} \int_\Omega v \frac{\partial v}{\partial n} \, d\ell + \frac{1}{2} \int_{\Gamma_2} q v^2 \, d\ell - \int_{\Gamma_2} g_2 v \, d\ell \]

\[ + w^2 \int_{\Gamma_1} (v - g_1)^2 \, d\ell - \alpha \int_{\Gamma_1} \frac{\partial v}{\partial n} (v - g_1) \, d\ell . \tag{2.24} \]

In the Penalty BAM, $w > 0$ and $\alpha = 0$; in the Hybrid BAM, $w = 0$ and $\alpha = 1$; and in the Penalty/Hybrid BAM, $w \geq 0$ and $0 \leq \alpha \leq 1$ with $w^2 + \alpha^2 > 0$. The functional (2.24) involves only boundary integrals. This is, of course, also true for the equivalent Galerkin problem: Find $u \in H^1(\Omega)$ such that

\[ \int_\Omega u \frac{\partial u}{\partial n} \, d\ell + \int_{\Gamma_2} q u v \, d\ell + 2w^2 \int_{\Gamma_1} u v \, d\ell - \alpha \int_{\Gamma_1} \left( \frac{\partial u}{\partial n} v + u \frac{\partial v}{\partial n} \right) \, d\ell = \]

\[ = \int_{\Gamma_2} g_2 v \, d\ell + 2w^2 \int_{\Gamma_1} g_1 v \, d\ell - \alpha \int_{\Gamma_1} g_1 \frac{\partial v}{\partial n} \, d\ell \quad \forall v \in H^1(\Omega). \tag{2.25} \]

The discrete problem is obtained by replacing $u$ with $u_N \in V_N \subset H^1(\Omega)$ above and requiring that (2.25) holds for all $v \in V_N$.

In the BAM with Lagrange multipliers, the functional

\[ I(v, \lambda) = \frac{1}{2} \int_\Omega v \frac{\partial v}{\partial n} \, d\ell + \frac{1}{2} \int_{\Gamma_2} q v^2 \, d\ell - \int_{\Gamma_2} g_2 v \, d\ell - \int_{\Gamma_1} \lambda (v - g_1) \, d\ell \tag{2.26} \]

is minimized over all $(v, \lambda) \in H^1(\Omega) \times H^{-1/2}(\Gamma_1)$. The similarity of the BAM with Lagrange multipliers with the Hybrid BAM is obvious; the main difference is that the normal derivative $\partial v/\partial n|_{\Gamma_1} = \lambda$ is treated as an additional unknown variable. This is usually approximated locally in terms of polynomial basis functions. For completeness, we state the associated Galerkin problem, which reads: Find $(u, \lambda) \in H^1(\Omega) \times H^{-1/2}(\Gamma_1)$ such that

\[ \int_\Omega u \frac{\partial u}{\partial n} \, ds + \int_{\Gamma_2} q u v \, d\ell - \int_{\Gamma_1} [\lambda v + \mu (u - g_1)] \, d\ell = \int_{\Gamma_2} g_2 v \, d\ell \tag{2.27} \]
for all \((v, \mu) \in H^1(\Omega) \times H^{-1/2}(\Gamma_1)\). As before, the discrete problem is obtained by replacing \((u, \lambda)\) above with \((u_N, \lambda_h) \in [V_N \times \Lambda_h] \subset \left[H^1(\Omega) \times H^{-1/2}(\Gamma_1)\right]\) and requiring that (2.27) holds for all \((v, \mu) \in (V_N \times \Lambda_h)\). The precise definition of the finite dimensional subspace \(\Lambda_h \subset H^{-1/2}(\Gamma_1)\) is given in Section 4.4 ahead.

3 Application of the BAMs to the Motz problem

The Motz problem [12] is a benchmark Laplace equation problem that is very often used for testing various special numerical methods proposed in the literature for the solution of elliptic boundary value problems with boundary singularities. Figure 1 shows the geometry and the boundary conditions as modified by Wait and Mitchell [19]. The boundary value problem is stated as follows:

\[
\Delta u = 0 \quad \text{in} \quad \Omega = \left\{ (x, y) \mid -1 \leq x \leq 1, \ 0 \leq y \leq 1 \right\}, \tag{3.1}
\]
\[
u_{|_{\Omega}} = 0, \tag{3.2}
\]
\[
u_{|_{\partial \Omega}} = 500, \tag{3.3}
\]
\[
\frac{\partial u}{\partial n} \bigg|_{\partial \Omega \cup \partial \text{AB\cupCD}} = 0. \tag{3.4}
\]

![Diagram of the Motz problem](image)

**Fig. 1.** Geometry and boundary conditions of the Motz problem.
A singularity arises at \( x = y = 0 \), where the boundary condition suddenly changes from \( u = 0 \) to \( \partial u / \partial y = 0 \). The local solution is given by

\[
 u = \sum_{i=1}^{\infty} a_i r^{(2i-1)/2} \cos \left( \left( \frac{2i - 1}{2} \right) \theta \right),
\]  

(3.5)

where \((r, \theta)\) are the polar coordinates centered at the origin. The above expansion is valid in the entire solution domain [11], with a radius of convergence at least as large as 2 [17]. The values of the coefficients \( a_i \), known as singular coefficients or generalized stress intensity factors are of interest. Rosser and Papamichael obtained the exact solution of the Motz problem using a conformal mapping technique and computed accurate approximations to the first twenty coefficients expressing them in terms of the coefficients in the series expansions of various elliptic functions and integrals involved in their conformal maps [14], [17].

Many special numerical schemes have been proposed for the solution of the Motz problem, including finite-difference, global-element, boundary-element and finite-element methods. Early works include those of Symm [18] and Papamichael and Symm [15] who developed singular boundary integral methods. Recent methods include those of Georgiou et al. [6] and Li and Lu [10]. The reader is referred to these papers for discussions about other numerical methods used for the solution of the Motz problem and the calculation of the singular coefficients, and for additional references.

Let us now consider the following approximation of the solution

\[
 u_N = \sum_{i=1}^{N} a_i^N \Phi_i,
\]  

(3.6)

where the basis functions

\[
 \Phi_i = r^{(2i-1)/2} \cos \left( \left( \frac{2i - 1}{2} \right) \theta \right)
\]  

(3.7)

are the singular functions appearing in the local solution expansion (3.5) and \( a_i^N \) are the approximations of the singular coefficients \( a_i \). Since the singular functions \( \Phi_i \) are solutions of the Laplace equation, the theory of the previous section applies with

\[
\Gamma_1 = \overline{OD} \cup \overline{AB}, \quad \Gamma_2 = \overline{OA} \cup \overline{BC} \cup \overline{CD},
\]  

(3.8)

\[
g_1|_{\overline{OD}} = 0, \quad g_1|_{\overline{AB}} = 500, \quad q|_{\Gamma_2} = 0 \quad \text{and} \quad g_2|_{\Gamma_2} = 0.
\]
Moreover, the essential boundary condition on \( \partial \mathcal{D} \) and the natural boundary condition on \( \partial \mathcal{A} \) are identically satisfied by all basis functions \( \Phi_k \). As a result, for all \( v \in V_N \)

\[
\int_{\partial \mathcal{D}} v \frac{\partial v}{\partial n} \, d\ell = \int_{\partial \mathcal{A}} v \frac{\partial v}{\partial n} \, d\ell = 0 .
\]

Therefore, the functional (2.24) becomes

\[
I(v) = \frac{1}{2} \int_{\Gamma^*} v \frac{\partial v}{\partial n} \, d\ell + w^2 \int_{\mathcal{AB}} (v - 500)^2 \, d\ell - \alpha \int_{\mathcal{AB}} \frac{\partial v}{\partial n} (v - 500) \, d\ell \tag{3.9}
\]

where

\[
\Gamma^* = \mathcal{AB} \cup \mathcal{BC} \cup \mathcal{CD},
\]

and the solution is sought in the space

\[
H^1_M(\Omega) \doteq \left\{ v \in H^1(\Omega) : \left. v \right|_{\partial \mathcal{D}} = \left. \frac{\partial v}{\partial n} \right|_{\mathcal{AB}} = 0 \right\} . \tag{3.11}
\]

For convenience, the minimization and Galerkin problems reached with the four BAMs studied in this work are summarized below.

**Penalty BAM**

**Minimization problem:** Minimize

\[
I_P(v) \doteq \frac{1}{2} \int_{\Gamma^*} v \frac{\partial v}{\partial n} \, d\ell + w^2 \int_{\mathcal{AB}} (v - 500)^2 \, d\ell, \quad v \in V_N \subset H^1_M(\Omega) \tag{3.12}
\]

**Galerkin problem:** Find \( u_N \in V_N \subset H^1_M(\Omega) \) such that \( \forall v \in V_N \subset H^1_M(\Omega) \)

\[
\int_{\Gamma^*} u_N \frac{\partial v}{\partial n} \, d\ell + 2w^2 \int_{\mathcal{AB}} u_N v \, d\ell = 2w^2 \int_{\mathcal{AB}} 500 v \, d\ell \tag{3.13}
\]
Hybrid BAM

Minimization problem: Minimize

\[ I_H(v) = \frac{1}{2} \int_{\Gamma^*} v \frac{\partial v}{\partial n} d\ell - \int_{\partial B} \frac{\partial v}{\partial n} (v - 500) d\ell, \quad v \in V_N \subset H^1_M(\Omega) \] (3.14)

Galerkin problem: Find \( u_N \in V_N \subset H^1_M(\Omega) \) such that \( \forall v \in V_N \subset H^1_M(\Omega) \)

\[ \int_{\Gamma^*} u_N \frac{\partial v}{\partial n} d\ell - \int_{\partial B} \left( \frac{\partial u_N}{\partial n} v + u_N \frac{\partial v}{\partial n} \right) d\ell = - \int_{\partial B} 500 \frac{\partial v}{\partial n} d\ell \] (3.15)

Penalty/Hybrid BAM

Minimization problem: Minimize

\[ I_{PH}(v) = \frac{1}{2} \int_{\Gamma^*} v \frac{\partial v}{\partial n} d\ell + w^2 \int_{\partial B} (v - 500)^2 d\ell - \alpha \int_{\partial B} \frac{\partial v}{\partial n} (v - 500) d\ell, \quad v \in V_N \subset H^1_M(\Omega) \] (3.16)

Galerkin problem: Find \( u_N \in V_N \subset H^1_M(\Omega) \) such that \( \forall v \in V_N \subset H^1_M(\Omega) \)

\[ \int_{\Gamma^*} u_N \frac{\partial v}{\partial n} d\ell + 2w^2 \int_{\partial B} u_N v d\ell - \alpha \int_{\partial B} \left( \frac{\partial u_N}{\partial n} v + u_N \frac{\partial v}{\partial n} \right) d\ell = \]

\[ = 2w^2 \int_{\partial B} 500 v d\ell - \alpha \int_{\partial B} 500 \frac{\partial v}{\partial n} d\ell \] (3.17)

BAM with Lagrange multipliers

Minimization problem: Minimize

\[ I_L(v, \lambda) = \frac{1}{2} \int_{\Gamma^*} v \frac{\partial v}{\partial n} d\ell - \int_{\partial B} \lambda (v - 500) d\ell, \quad (v, \lambda) \in [V_N \times \Lambda_h] \subset [H^1_M(\Omega) \times H^{-1/2}(\partial B)] \] (3.18)

Galerkin problem: Find \( (u_N, \lambda_h) \in [V_N \times \Lambda_h] \subset [H^1_M(\Omega) \times H^{-1/2}(\partial B)] \) such
that $\forall (v, \mu) \in [V_N \times \Lambda_h] \subset \left[H^1_M(\Omega) \times H^{-1/2}(\partial \Omega)\right]$

$$\int_{\Gamma_N} u_N \frac{\partial v}{\partial n} \, d\ell - \int_{\partial \Omega} [\lambda_h \, v + \mu (u_N - 500)] \, d\ell = 0$$  (3.19)

4 Error analyses

Before proceeding to the error analyses for the four BAMs, we first provide some useful results, which, for the sake of simplicity, are presented specifically for the Motz problem. We will often use the notation $\beta \approx \gamma$ to mean that there exist constants $C_1$ and $C_2$ such that

$$C_1 \beta \leq \gamma \leq C_2 \beta.$$  

Also, throughout this section, the letters $c$ and $C$ denote generic positive constants which are generally different in each occurrence. Finally, we note that the error analyses that follow will give bounds on the error in approximating $u$ by $u_N$; error bounds for the singular coefficients can be obtained from these and the fact that [9]:

$$|a_i - a_i^N| \leq C \|u - u_N\|_{L^2(\Omega)}$$  (4.1)

with $C$ a positive constant independent of $N$.

**Lemma 4.1** Let $v$ satisfy (3.1)–(3.4) and let $\Gamma_1$ be given by (3.8). Then

$$|v|_{1,\Omega}^2 + \|v\|_{0, \partial \Gamma_1}^2 \approx \|v\|_{1,\Omega}^2.$$  (4.2)

**Proof:** We first have

$$|v|_{1,\Omega}^2 + \|v\|_{0, \partial \Gamma_1}^2 \leq |v|_{1,\Omega}^2 + \|v\|_{0, \Omega}^2 = \|v\|_{1,\Omega}^2.$$  (4.3)

Next we use Poincaré’s inequality to obtain

$$C \|v\|_{1,\Omega}^2 \leq |v|_{1,\Omega}^2 + \|v\|_{0, \partial \Gamma_1}^2.$$  (4.4)

Combining (4.3) and (4.4) we get (4.2).
In what follows we will be using the norm

\[ \|v\|_H = \left\{ \int_{\Gamma} v \frac{\partial v}{\partial n} + w^2 \int_{\Omega} v^2 \right\}^{1/2} \quad (4.5) \]

for \( w \geq 1 \), with \( \Gamma^* \) given by (3.10).

**Lemma 4.2** If \( w = 1 \), then \( \|v\|_H \approx \|v\|_{1,\Omega} \) \( \forall v \in V_N \).

**Proof:** Let \( v \in V_N \) and note that

\[ \Delta v = 0 \text{ in } \Omega, \quad v|_{\partial \Omega} = 0, \quad \frac{\partial v}{\partial n}|_{\partial \Omega} = 0. \quad (4.6) \]

Using Green’s formula, we have

\[ |v|_{1,\Omega}^2 = \iint_{\Omega} |\nabla v|^2 = \iint_{\Omega} v \Delta v + \int_{\partial \Omega} v \frac{\partial v}{\partial n} \]

and by (4.6)

\[ |v|_{1,\Omega}^2 = \int_{\Gamma} v \frac{\partial v}{\partial n}. \quad (4.7) \]

Now, since \( w = 1 \), we have from (4.5)

\[ \|v\|_H^2 = \int_{\Gamma} v \frac{\partial v}{\partial n} + \int_{\Omega} v^2 \]

and by (4.7)

\[ \|v\|_H^2 = |v|_{1,\Omega}^2 + \|v\|_{0,\Gamma}^2. \]

The desired result follows as in the proof of Lemma 4.1.

**Lemma 4.3** For \( w \geq 1 \), there exist constants \( C_1, C_2 > 0 \) such that

\[ C_1 \|v\|_{1,\Omega} \leq \|v\|_H \leq C_2 w \|v\|_{1,\Omega} \forall v \in V_N. \quad (4.8) \]

**Proof:** Let \( \Gamma_1 \) be given by (3.8). Since \( w \geq 1 \), we have

\[ \|v\|_H^2 \geq |v|_{1,\Omega}^2 + \|v\|_{0,\Gamma}^2, \]

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and by Lemma 4.1
\[ \|v\|_H^2 \geq C \|v\|_{1,\Omega}^2. \] (4.9)

Next, we have
\[ \|v\|_H^2 = w^2 \left\{ \frac{1}{w^2} \|v\|_{1,\Omega}^2 + \|v\|_{0,\Gamma_1}^2 \right\} \leq C w^2 \left\{ \|v\|_{1,\Omega}^2 + \|v\|_{0,\Gamma_1}^2 \right\} \]

and by Lemma 4.2
\[ \|v\|_H^2 \leq C w^2 \|v\|_{1,\Omega}^2. \] (4.10)

Combining (4.9) and (4.10) we get (4.8).

Now, let \( u = \overline{u}_N + r_N \) with
\[ \overline{u}_N = \sum_{i=1}^{N} a_i \Phi_i \] (4.11)

and
\[ r_N = \sum_{i=N+1}^{\infty} a_i \Phi_i, \] (4.12)

where \( a_i \) are the true singular coefficients and \( \Phi_i \) are given by (3.7). We have the following lemma.

**Lemma 4.4** With \( r_N \) given by (4.12) we have
\[ \|r_N\|_H \leq \|r_N\|_{0,\Gamma^*}^{1/2} \left\| \frac{\partial r_N}{\partial n} \right\|_{0,\Gamma^*}^{1/2} + w \|r_N\|_{0,\Gamma^*}. \]

**Proof:** Using (4.5) and the Cauchy-Schwarz inequality, we get
\[ \|r_N\|_H^2 \leq \|r_N\|_{0,\Gamma^*} \left\| \frac{\partial r_N}{\partial n} \right\|_{0,\Gamma^*} + w^2 \|r_N\|_{0,\Gamma^*}^2. \]

Using the inequality \( \sqrt{a^2 + b^2} \leq a + b \), the desired result follows.
In what follows, we make the assumption that there exists \( a \in (0,1) \) such that, with \( r_N \) is given by (4.12),

\[
\|r_N\|_{0,\Gamma^*} \leq Ca^N, \tag{4.13}
\]

\[
\left\| \frac{\partial r_N}{\partial n} \right\|_{0,\Gamma^*} \leq CNa^N, \tag{4.14}
\]

where \( C \) is a constant independent of \( N \).

Assumptions (4.13)–(4.14) hold trivially if \( r < 1 \) in the local solution (3.5), since then by (3.7), (4.12) and the fact that the solution \( u \) is continuous, we have

\[
|r_N| \leq \sum_{i=N+1}^{\infty} |a_i| r^{i-\frac{1}{2}} \leq C \frac{r^{N+\frac{1}{2}}}{1 - r} \leq Ca^N
\]

with \( r < a < 1 \). In the case of \( r \geq 1 \), one may partition the domain \( \Omega \) into subdomains in which separate approximations may be obtained, as was discussed in Section 1. The solution over the entire domain can then be composed by combining the solutions from the various subdomains and properly dealing with their interactions across the interfaces separating each subdomain (see, e.g., [8]).

4.1 The Penalty BAM

Using the above results, we arrive at the following theorem for the Penalty BAM.

**Theorem 4.1.** Let \( u^P_N \in V_N \) be the solution to (3.12) and \( u \in H^1_\Gamma \) the weak solution to (3.1)–(3.4). Then, there exists a positive constant \( C \), independent of \( N \), such that

\[
\|u - u^P_N\|_H \leq C \left\{ \inf_{v \in V_N} \|u - v\|_H + \frac{1}{w} \left\| \frac{\partial u}{\partial n} \right\|_{0,\partial H} \right\}.
\]

**Proof:** Note that \( u^P_N \in V_N \) satisfies

\[
B_1(u^P_N, v) = F_1(v) \quad \forall v \in V_N \tag{4.15}
\]
where
\[ B_1(u, v) = \int_\Gamma v \frac{\partial u}{\partial n} + w^2 \int_{\partial \Omega} uv, \quad F_1(v) = 500 w^2 \int_{\partial \Omega} v. \]

In addition, \( u \) satisfies
\[ B_1(u, v) = F_1(v) + \int_{\partial \Omega} v \frac{\partial u}{\partial n} \quad \forall \, v \in H^1_M. \tag{4.16} \]

Combining (4.15) and (4.16) we get
\[ B_1(u - u_N^r, v) = \int_{\partial \Omega} v \frac{\partial u}{\partial n} \quad \forall \, v \in V_N. \tag{4.17} \]

Let \( \delta = (u_N^r - v) \in V_N \). Then, using (4.5) and (4.17), we obtain
\[ \| \delta \|_H = B_1(\delta, \delta) = B_1(u_N^r - v, \delta) = B_1(u - v, \delta) - \int_{\partial \Omega} \frac{\partial u}{\partial n}. \tag{4.18} \]

Since \( |B_1(u, v)| \leq C \| u \|_H \| v \|_H \), we further obtain
\[ \| \delta \|_H^2 \leq C \| u - v \|_H \| \delta \|_H + \| \delta \|_{0, \partial \Omega} \left\| \frac{\partial u}{\partial n} \right\|_{0, \partial \Omega} \]

after using the triangle and Cauchy-Schwartz inequalities. By Lemma 4.3,
\[ \| \delta \|_{0, \partial \Omega} \leq C \frac{1}{w} \| \delta \|_H \]

hence
\[ \| \delta \|_H^2 \leq C \left\{ \| u - v \|_H + \frac{1}{w} \left\| \frac{\partial u}{\partial n} \right\|_{0, \partial \Omega} \right\} \| \delta \|_H. \]

Dividing by \( \| \delta \|_H \) we get
\[ \| \delta \|_H \leq C \left\{ \| u - v \|_H + \frac{1}{w} \left\| \frac{\partial u}{\partial n} \right\|_{0, \partial \Omega} \right\} \quad \forall \, v \in V_N. \tag{4.19} \]
Finally,
\[ \| u - u_N^p \|_H \leq \| u - v \|_H + \| v - u_N^p \|_H \leq C \left\{ \| u - v \|_H + \frac{1}{w} \left\| \frac{\partial u}{\partial n} \right\|_{0, \partial B} \right\} \]
and the proof is complete.

**Corollary 4.1** Let \( u \) be the weak solution to (3.1)–(3.4) and let \( u_N^p \) satisfy (3.12). Then, there exists a constant \( C > 0 \), independent of \( N \) such that
\[ \| u - u_N^p \|_H \leq C \left\{ \| r_N \|_H^{1/2} \left\| \frac{\partial r_N}{\partial n} \right\|_H^{1/2} + w \| r_N \|_{0, \partial B} + \frac{1}{w} \right\}. \] (4.20)

**Proof:** Let \( v = \overline{u}_N \) and \( u = \overline{u}_N + r_N \) as given by (4.11) and (4.12). Then, by Theorem 4.1
\[ \| u - u_N^p \|_H \leq C \left\{ \inf_{r_N \in V} \| u - v \|_H + \frac{1}{w} \left\| \frac{\partial u}{\partial n} \right\|_{0, \partial B} \right\} \]
\[ \leq C \left\{ \| r_N \|_H + \frac{1}{w} \left\| \frac{\partial u}{\partial n} \right\|_{0, \partial B} \right\}. \]
The desired result follows from Lemma 4.4 and by noting that \( \left\| \frac{\partial u}{\partial n} \right\|_{0, \partial B} \leq C. \n
Assuming (4.13) and (4.14) hold, we may use Corollary 4.1 to obtain the optimal choice for the parameter \( w = a^{-N/2} \) for the Penalty BAM, as well as the error estimate
\[ \| u - u_N^p \|_H \leq C \sqrt{N} a^{N/2} \] (4.21)
with \( C \) a constant independent of \( N \) and \( a \).

**4.2 The Hybrid BAM**

In the Hybrid BAM, we seek \( u_N^H \in V_N \) such that (3.15) holds \( \forall \, v \in V_N \) (with \( u_N \) replaced by \( u_N^H \)). Note that \( u_N^H \) also satisfies
\[ B_2(u_N^H, v) = F_2(v) \quad \forall \, v \in V_N, \] (4.22)
where
\[
B_2(u, v) = \int u \frac{\partial v}{\partial n} - \int v \frac{\partial u}{\partial n} - \int u \frac{\partial v}{\partial n} = \int v \frac{\partial u}{\partial n} + \int u \frac{\partial v}{\partial n} \quad (4.23)
\]
and
\[
F_2(v) = -500 \int \frac{\partial v}{\partial n}. \quad (4.24)
\]

We have the following theorem.

**Theorem 4.2** Let \( u^H_N \in V_N \) satisfy (4.22) and \( u \in H^1_M \) be the weak solution to (3.1)--(3.4). Then
\[
|u - u^H_N|_{1, \Omega} \leq 2 \inf_{v \in V_N} |u - v|_{1, \Omega}.
\]

**Proof:** Note that
\[
B_2(v, v) = \int v \frac{\partial v}{\partial n} = \int_{\Omega} |\nabla v|^2 = |v|_{1, \Omega}^2 \quad \forall v \in V_N.
\]

Moreover, with \( u \in H^1_M \) the solution to (3.1)--(3.4), we have
\[
B_2(u - u^H_N, v) = 0 \quad \forall v \in V_N. \quad (4.25)
\]

Let \( \delta = (u^H_N - v) \in V_N \) with \( v \in V_N \) arbitrary. Then
\[
|\delta|_{1, \Omega}^2 = B_2(\delta, \delta) = B_2(u^H_N - v, \delta)
\]
so that using (4.25)
\[
|\delta|_{1, \Omega}^2 = B_2(u^H_N - v, \delta) + B_2(u - u^H_N, \delta) = B_2(u - v, \delta)
\]
\[
\leq |B_2(u - v, u - v) B_2(\delta, \delta)|^{1/2} = |u - v|_{1, \Omega} |\delta|_{1, \Omega}
\]
which gives
\[
|\delta|_{1, \Omega} \leq |u - v|_{1, \Omega}.
\]
Thus, with \( v \in V_N \)
\[
|u - u_N^H|_{1, \Omega} \leq |u - v|_{1, \Omega} + |v - u_N^H|_{1, \Omega} = |u - v|_{1, \Omega} + \delta|_{1, \Omega} \leq 2|u - v|_{1, \Omega}
\]
from which the desired result follows.

**Corollary 4.2** Let the assumptions of Theorem 4.2 as well as (4.13)–(4.14) hold. Then
\[
\|u - u_N^H\|_{1, \Omega} \leq C\sqrt{N\alpha}^N
\]
where \( C \) is a constant independent of \( N \) and \( \alpha \in (0, 1) \).

**Proof:** By Poincaré’s inequality and Theorem 4.2,
\[
\|u - u_N^H\|_{1, \Omega} \leq C(\Omega)|u - u_N^H|_{1, \Omega} < 2C(\Omega) \inf_{v \in V_N} |u - v|_{1, \Omega}.
\]

Letting \( v = \pi_N, u = \pi_N + r_N \) and using (4.7), (4.13) and (4.14) we get
\[
\|u - u_N^H\|_{1, \Omega} < C|r_N|_{1, \Omega} \leq CNa^N
\]
as desired.

Comparing the above result with the error bound (4.21), we see that the Hybrid BAM converges at an optimal rate.

### 4.3 The Penalty/Hybrid BAM

Recall that \( u_N^{PH} \) is obtained from
\[
I_{PH}(u_N^{PH}) = \min_{v \in V_N} I_{PH}(v)
\]
(4.26)
where \( I_{PH}(v) \) is defined by (3.16). Equivalently, we may seek \( u_N^{PH} \in V_N \) such that
\[
B_3(u_N^{PH}, v) = F_3(v) \ \forall v \in V_N
\]
(4.27)
where
\[
B_3(u, v) = \int_G u \frac{\partial v}{\partial n} + 2w^2 \int AB uv - \alpha \int AB \left( \frac{\partial u}{\partial n} + u \frac{\partial v}{\partial n} \right),
\]
(4.28)
\[
F_3(v) = 2w^2 \int_{\pi \mathbb{B}} 500v - \alpha \int_{\pi \mathbb{B}} 500 \frac{\partial v}{\partial n}. \tag{4.29}
\]

First, let us consider how to choose the two parameters \( \alpha \) and \( w \) above. The value of \( w \) must be chosen in such a way that the first two integrals in (3.16) are balanced. To this end, let us, for simplicity, restrict our consideration to a semi-circular domain

\[
S_R = \{(r, \theta) : 0 \leq r \leq R, 0 \leq \theta \leq \pi \}, \tag{4.30}
\]

with boundary

\[
\ell_R = \{(R, \theta) : 0 \leq \theta \leq \pi \}, \tag{4.31}
\]

for which the following result holds.

**Lemma 4.5** Let \( \ell_R \) be given by (4.31). Then, for any \( v \in V_N \)

\[
\int_{\ell_R} v \frac{\partial v}{\partial n} \leq \frac{N + 1}{R} \int_{\ell_R} v^2, \tag{4.32}
\]

\[
\int_{\ell_R} \left( \frac{\partial v}{\partial n} \right)^2 \leq \frac{N + 1}{R^2} \int_{\ell_R} v^2. \tag{4.33}
\]

**Proof:** Since \( v \in V_N \) we have

\[
v = \sum_{i=1}^{N} \beta_i r^{(2i-1)/2} \cos \left( \frac{2i - 1}{2} \theta \right) \tag{4.34}
\]

with \( \beta_i \in \mathbb{R} \). By direct calculation, using the orthogonality of trigonometric functions, we obtain

\[
\int_{\ell_R} v^2 = \frac{\pi}{2} \sum_{i=1}^{N} (\beta_i)^2 R^{2i} \tag{4.35}
\]

\[
\int_{\ell_R} v \frac{\partial v}{\partial n} = \frac{\pi}{2} \sum_{i=1}^{N} (\beta_i)^2 (2i - 1) R^{2i-1} \tag{4.36}
\]

\[
\int_{\ell_R} \left( \frac{\partial v}{\partial n} \right)^2 = \frac{\pi}{2} \sum_{i=1}^{N} (\beta_i)^2 (2i - 1)^2 R^{2i-2}. \tag{4.37}
\]
From (4.36), we get

\[
\int_{\Omega} v \frac{\partial v}{\partial n} = \frac{\pi}{2} \sum_{i=1}^{N} (\beta_i)^2 (2i - 1) R^{2i-1} = \frac{1}{R^2} \sum_{i=1}^{N} (\beta_i) R^{2i}
\]

which along with (4.35) gives (4.32). Similarly, from (4.37)

\[
\int_{\Omega} \left( v \frac{\partial v}{\partial n} \right)^2 = \frac{\pi}{2} \sum_{i=1}^{N} (\beta_i)^2 (2i - 1)^2 R^{2i-2} = \frac{1}{R^2} \sum_{i=1}^{N} (\beta_i) R^{2i}
\]

which along with (4.35) gives (4.33), and the proof is complete.

Guided by (4.32) in the above lemma, we return to our problem and choose \( w^2 = C^*(N + 1) \), where \( C^* \in \mathbb{R}^+ \) will be determined shortly. Moreover, in view of (4.33), we make the following assumption: \( \exists C \in \mathbb{R} \) independent of \( N \) such that

\[
\left\| v \right\|_{0, \partial B} \leq C (N + 1) \left\| v \right\|_{0, \Omega} \quad \forall v \in V_N. \tag{4.38}
\]

In what follows we will obtain error bounds for this method in the norm

\[
\| v \|_* = \left( \| v \|_{1, \Omega}^2 + w^2 \| v \|_{0, \partial B}^2 \right)^{1/2} = \left( \| v \|_{1, \Omega}^2 + C^*(N + 1) \| v \|_{0, \partial B}^2 \right)^{1/2}. \tag{4.39}
\]

We have the following lemma.

**Lemma 4.6** Suppose (4.38) holds. Then, for \( \alpha \in (0, 1] \) there exists \( C^* \in \mathbb{R} \) independent of \( N \), such that

\[
B_3 (v, v) \geq \| v \|_*^2 \quad \forall v \in V_N \tag{4.40}
\]

and

\[
| B_3 (u, v) | \leq C \| u \|_* \| v \|_* \quad \forall u, v \in V_N \tag{4.41}
\]

with \( C \in \mathbb{R} \) independent of \( N \).
Proof: Note that $B_3(u,v)$ given by (4.28) may be written as

$$B_3(u,v) = \int_{\Omega} \nabla u \cdot \nabla v + 2C^*(N + 1) \int_{AB} uv - \alpha \int_{AB} \left( \frac{\partial u}{\partial n} + u \frac{\partial v}{\partial n} \right)$$  

(4.42)

so that

$$B_3(v,v) = \int_{\Omega} |\nabla v|^2 + 2C^*(N + 1) \int_{AB} v^2 - 2\alpha \int_{AB} \frac{\partial v}{\partial n} v.$$  

(4.43)

Using the Cauchy-Schwartz inequality and (4.38),

$$\int_{AB} \frac{\partial v}{\partial n} \leq \left\| \frac{\partial v}{\partial n} \right\|_{0,AB} \leq C(N + 1) \| v \|_{0,AB}$$  

(4.44)

Hence

$$B_3(v,v) \geq \int_{\Omega} |\nabla v|^2 + 2 (C^* - C\alpha)(N + 1) \| v \|_{0,AB}^2$$  

(4.45)

where $C \in \mathbb{R}$ is the constant in (4.44). Choosing $C^* \in \mathbb{R}$ to satisfy $2(C^* - C\alpha) \geq C^*$, i.e.

$$C^* \geq 2C\alpha$$  

(4.46)

gives

$$B_3(v,v) \geq \int_{\Omega} |\nabla v|^2 + C^*(N + 1) \| v \|_{0,AB}^2 = \| v \|_*^2$$  

(4.47)

which is precisely (4.40).

Next, we have

$$|B_3(u,v)| \leq \int_{\Omega} \nabla u \cdot \nabla v + 2C^*(N + 1) \int_{AB} uv +$$

$$+ \alpha \left( \left\| \frac{\partial u}{\partial n} \right\| + \left\| \frac{\partial u}{\partial n} \right\| + \left\| u \frac{\partial v}{\partial n} \right\| \right).$$  

(4.48)
Moreover,
\[
\left| \int_{\partial B} \frac{\partial u}{\partial n} v \right| \leq C \| u \|_{1, \Omega} \| v \|_{1, \Omega} \leq C \| u \|_* \| v \|_* \tag{4.49}
\]
and similarly
\[
\left| \int_{\partial B} \frac{\partial v}{\partial n} u \right| \leq C \| u \|_* \| v \|_* \tag{4.50}
\]
Combining (4.48)–(4.50) we get
\[
|B_3(u, v)| \leq \left| \int \nabla u \cdot \nabla v \right| + 2C^* (N + 1) \left| \int_{\partial B} w \right| + C \alpha \| u \|_* \| v \|_*
\leq |u|_{1, \Omega} |v|_{1, \Omega} + 2C^* (N + 1) \| u \|_{0, \partial B} \| v \|_{0, \partial B} + C \alpha \| u \|_* \| v \|_*
\leq (1 + C \alpha) \| u \|_* \| v \|_*
\]
from which (4.41) follows.

Using the above lemma, we obtain the following result.

**Theorem 4.3** Let \( u_N^{PH} \in V_N \) satisfy (4.27) and \( u \in H^1_M \) be the weak solution to (3.1)–(3.4). Assuming (4.38) holds, there exists a constant \( C \), independent of \( N \), such that
\[
\| u - u_N^{PH} \|_* \leq C \left\{ \inf_{v \in V_N} \| u - v \|_* + \frac{|1 - \alpha|}{\sqrt{C^* (N + 1)}} \left| \frac{\partial u}{\partial n} \right|_{0, \partial B} \right\}. \tag{4.51}
\]

**Proof:** With \( u \in H^1_* \) the weak solution to (3.1)–(3.4), we have from (4.28), (4.29)
\[
B_3(u, v) = (1 - \alpha) \int_{\partial B} \frac{\partial u}{\partial n} v + F_3(v) \tag{4.52}
\]
so that using (4.27) and (4.39),
\[ B_3(u - u_{N}^{PH}, v) = (1 - \alpha) \int_{\partial B} \frac{\partial u}{\partial n} v \leq |1 - \alpha| \left\| \frac{\partial u}{\partial n} \right\|_{0, \partial B} \left\| v \right\|_{0, \partial B} \leq C \frac{|1 - \alpha|}{\sqrt{C^{*} (N + 1)}} \left\| \frac{\partial u}{\partial n} \right\| \left\| v \right\|_{*}. \]

With \( v \in V_N \), let \( \delta = (v - u_{N}^{PH}) \in V_N \). By Lemma 4.6,

\[ \left\| \delta \right\|_{*}^{2} \leq B_3(\delta, \delta) = B_3(v - u_{N}^{PH}, \delta) = B_3(u - v, \delta) = (1 - \alpha) \int_{\partial B} \frac{\partial u}{\partial n} \delta \]

\[ \leq C \left\{ \left\| u - v \right\|_{*} \left\| \delta \right\|_{*} + \frac{|1 - \alpha|}{\sqrt{C^{*} (N + 1)}} \left\| \frac{\partial u}{\partial n} \right\| \left\| \delta \right\|_{*} \right\}. \]

Hence

\[ \left\| \delta \right\|_{*} \leq C \left\{ \left\| u - v \right\|_{*} + |1 - \alpha| \sqrt{C^{*} (N + 1)} \left\| \frac{\partial u}{\partial n} \right\|_{0, \partial B} \right\}. \] (4.53)

Therefore, by the triangle inequality and (4.53)

\[ \left\| u - u_{N}^{PH} \right\|_{*} \leq \left\| u - v \right\|_{*} + \left\| v - u_{N}^{PH} \right\|_{*} = \left\| u - v \right\|_{*} + \left\| \delta \right\|_{*} \]

\[ \leq \left\| u - v \right\|_{*} + C \left\{ \left\| u - v \right\|_{*} + \frac{|1 - \alpha|}{\sqrt{C^{*} (N + 1)}} \left\| \frac{\partial u}{\partial n} \right\|_{0, \partial B} \right\} \]

and the proof is complete.

Based on Theorem 4.3, we could choose the parameter \( \alpha = 1 \) in order to raise the accuracy of the method. In this case, we have the following theorem.

**Theorem 4.4** Let the assumptions of Theorem 4.3 and (4.13)–(4.14) hold, and choose \( \alpha = 1 \). Then there exists a constant \( C \) independent of \( N \) such that

\[ \left\| u - u_{N}^{PH} \right\|_{*} \leq C \sqrt{Na^{N}} \] (4.54)

with \( a \in (0, 1) \).

**Proof:** With \( \alpha = 1 \), we have from Theorem 4.3,

\[ \left\| u - u_{N}^{PH} \right\|_{*} \leq C \inf_{v \in V_N} \left\| u - v \right\|_{*}. \] (4.55)
Letting $u = \overline{\nu} + r_N$ with $\overline{\nu}$ and $r_N$ given by (4.11) and (4.12), we further have
\[
\left\| u - u_N^{PH} \right\| \leq C \left\| r_N \right\| = C \left( \left\| r_N \right\|_{1, \Omega} + C^* (N + 1) \left\| r_N \right\|_{0, \overline{AB}}^{1/2} \right),
\] (4.56)
and by (4.13)
\[
\left\| u - u_N^{PH} \right\| \leq C \left( \left\| r_N \right\|_{1, \Omega}^2 + N \alpha^{2N} \right)^{1/2} \leq C \left( \left\| r_N \right\|_{1, \Omega} + \sqrt{N} \alpha^N \right).
\] (4.57)

It remains to bound $\left\| r_N \right\|_{1, \Omega}$ in (4.57). By (4.7), (4.13) and (4.14) we have
\[
\left\| r_N \right\|_{1, \Omega}^2 = \int_{\Gamma} \frac{\partial v}{\partial n} \leq C \left\| \frac{\partial r_N}{\partial n} \right\|_{0, \overline{AB}} \left\| r_N \right\|_{0, \overline{AB}} \leq C N \alpha^{2N}
\] (4.58)
so that combined with (4.57) gives the desired result.

We should point out that the parameter $w^2 = C^* (N + 1)$ includes the constant $C^*$ satisfying (4.46); in practice it turns out that simply choosing $C^* = 1$ suffices, as observed in the numerical computations of Section 5.

### 4.4 The BAM with Lagrange Multipliers

When the Dirichlet condition $u|_{\overline{AB}} = 500$ is regarded as a constraint, the solution to the Motz problem may be obtained by minimizing the (not positive definite) functional $I_L(v)$ given by (3.18), or equivalently by solving the variational problem given by (3). While for the implementation of the method (3) is used, for the analysis it is often convenient to state the variational problem as follows: Find $(u, \lambda) \in H^1_M(\Omega) \times H^{-1/2} \left( \overline{AB} \right)$ such that
\[
B(u, v) + G(u, v; \lambda, \mu) = 0, \quad \forall (v, \mu) \in H^1_M(\Omega) \times H^{-1/2} \left( \overline{AB} \right),
\] (4.59)
where
\[
B(u, v) = \int_{\Omega} \nabla v \cdot \nabla u,
\] (4.60)
\[
G(u, v; \lambda, \mu) = - \int_{\overline{AB}} v \lambda - \int_{\overline{AB}} \mu (u - 500).
\] (4.61)
For the discretization, we divide \( AB \) into sections \( \Gamma_i, i = 1, \ldots, n \), such that

\[
AB = \bigcup_{i=1}^{n} \Gamma_i, \quad h_i = |\Gamma_i|, \quad h = \max_{1 \leq i \leq n} h_i.
\]

(4.62)

With \( \mathcal{P}_k(AB) \) the space of polynomials of degree \( \leq k \) on \( AB \), we define

\[
\Lambda_h = \{ \lambda_h : \lambda_h|_{\Gamma_i} \in \mathcal{P}_k(\Gamma_i), i = 1, \ldots, n \}.
\]

(4.63)

Then, the discrete version of (4.59) reads: Find \( (u_N^L, \lambda_h) \in V_N \times \Lambda_h \) such that

\[
B(u_N^L, v) + G(u_N^L, v; \lambda_h, \mu) = 0 \quad \forall \ (v, \mu) \in V_N \times \Lambda_h
\]

(4.64)

The present method was first introduced in [6] and was subsequently used to efficiently solve Laplacian problems in domains with boundary singularities (cf. [4], [5]). Below we give a brief justification for the method, as it pertains to the Motz problem. We begin with the following theorem from [9].

**Theorem 4.5** Let \( (u, \lambda) \) and \( (u_N^L, \lambda_h) \) be the solutions to (4.59) and (4.64), respectively. Suppose there exist positive constants \( c_0, c, \beta \) and \( \gamma \), independent of \( N \) and \( h \), such that the following assumptions hold:

\[
B(v, v) \geq c_0 \|v\|_{1, \Omega}^2 \quad \text{and} \quad |B(u, v)| \leq c \|u\|_{1, \Omega} \|v\|_{1, \Omega} \quad \forall \ v \in V_N,
\]

(4.65)

\[
\exists \ 0 \neq v_N \in V_N \ s.t. \ \int_{AB} \mu_h v_N \geq \beta \|\mu_h\|_{-1/2, \partial AB} \|v_N\|_{1, \Omega} \quad \forall \ \mu_h \in \Lambda_h,
\]

(4.66)

\[
\int_{AB} \lambda v \leq \gamma \|\lambda\|_{-1/2, \partial AB} \|v\|_{1, \Omega} \quad \forall \ v_N \in V_N.
\]

(4.67)

Then,

\[
\left\| u - u_N^L \right\|_{1, \Omega} + \|\lambda - \lambda_h\|_{-1/2, \partial AB} \leq C \left\{ \inf_{v \in V_N} \left\| u - v \right\|_{1, \Omega} + \inf_{\eta \in \Lambda_h} \left\| \lambda - \eta \right\|_{-1/2, \partial AB} \right\}
\]

with \( C \in \mathbb{R}^+ \) independent of \( N \) and \( h \).

**Proof:** For a proof see Theorem 6.1 in [9].

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Let us verify that (4.65)–(4.67) hold for our problem. First, note that $B(v, v) = |v|^2_{1, \Omega}$ so that, by Poincaré’s inequality

$$B(v, v) \geq c_0 \|v\|^2_{1, \Omega} \quad \forall v \in H^1_M(\Omega).$$

By the Cauchy-Schwartz inequality,

$$B(u, v) \leq c \|u\|_{1, \Omega} \|v\|_{1, \Omega} \quad \forall u, v \in H^1_M(\Omega)$$

so that (4.68) and (4.69) give (4.65).

To verify (4.66), consider the following auxiliary problem: Find $w \in H^1_M(\Omega)$ such that

$$\Delta w = 0 \text{ in } \Omega$$

$$\frac{\partial w}{\partial n} = \mu_h \text{ on } AB$$

$$w = 0 \text{ on } OD$$

$$\frac{\partial w}{\partial n} = 0 \text{ on } OA \cup BC \cup CD$$

where $\mu_h \in \Lambda_h$ in (4.71). From (4.70)–(4.71) we obtain, using Green’s formula and Poincaré’s inequality,

$$\int_{AB} \mu_h w = \int_{AB} w \frac{\partial w}{\partial n} = \iint_{\Omega} w \Delta w + \iint_{\Omega} |\nabla w|^2 = \|w\|_{1, \Omega}^2 \geq c_0 \|w\|_{1, \Omega}^2$$

with $c_0 \in \mathbb{R}^+$. Also,

$$\|\mu_h\|_{-1/2, AB} = \left\| \frac{\partial w}{\partial n} \right\|_{-1/2, AB} \leq C \|w\|_{1, \Omega}$$

so that by (4.74)–(4.75)

$$\int_{AB} \mu_h w \geq c_0 \|w\|_{1, \Omega}^2 \geq \beta \|w\|_{1, \Omega} \|\mu_h\|_{-1/2, AB}$$

with $\beta \in \mathbb{R}^+$ independent of $w$ and $h$. Now, let $w_N \in V_N$ be such that $w = w_N + r_N$ with $r_N \in H^1_M(\Omega)$ the remainder (see (4.11)–(4.14)). We have

$$\int_{AB} \mu_h w_N = \int_{AB} \mu_h w - \int_{AB} \mu_h r_N$$

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and also
\[
\int \frac{\mu_h r_N}{\overline{AB}} \leq \|\mu_h\|_{-1/2,\overline{AB}} \|r_N\|_{1/2,\overline{AB}} \leq C_1 \|\mu_h\|_{-1/2,\overline{AB}} \|r_N\|_{1,\Omega},
\] (4.78)

so that combining (4.76)–(4.78) we get
\[
\int \frac{\mu_h w_N}{\overline{AB}} \geq \beta \|w\|_{1,\Omega} \|\mu_h\|_{-1/2,\overline{AB}} - C_1 \|\mu_h\|_{-1/2,\overline{AB}} \|r_N\|_{1,\Omega}.
\] (4.79)

Now, using
\[
\|w\|_{1,\Omega} = \|w_N + r_N\|_{1,\Omega} \geq \|w_N\|_{1,\Omega} - \|r_N\|_{1,\Omega}
\]
along with (4.79), we obtain
\[
\int \frac{\mu_h w_N}{\overline{AB}} \geq \beta \left(\|w_N\|_{1,\Omega} - \|r_N\|_{1,\Omega}\right) \|\mu_h\|_{-1/2,\overline{AB}} - C_1 \|\mu_h\|_{-1/2,\overline{AB}} \|r_N\|_{1,\Omega}
\]
\[
\geq \beta \|w_N\|_{1,\Omega} \|\mu_h\|_{-1/2,\overline{AB}} - (C_1 + \beta) \|\mu_h\|_{-1/2,\overline{AB}} \|r_N\|_{1,\Omega}.
\] (4.80)

Since, by assumptions (4.13)–(4.14), \(w_N\) converges to \(w\) exponentially, we have
\[
0 < \frac{\|r_N\|_{1,\Omega}}{\|w_N\|_{1,\Omega}} < 1.
\]

For \(N\) sufficiently large, we may write
\[
\frac{\|r_N\|_{1,\Omega}}{\|w_N\|_{1,\Omega}} \leq \frac{\beta}{2(C_1 + \beta)}
\] (4.81)

where \(C_1\) and \(\beta\) are the positive constants from above. Combining (4.80) and (4.81) we have
\[
\int \frac{\mu_h w_N}{\overline{AB}} \geq \frac{\beta}{2} \|\mu_h\|_{-1/2,\overline{AB}} \|w_N\|_{1,\Omega}
\]

which gives (4.66) once we replace \(w_N\) by \(v_N\) and \(\beta/2\) by \(\beta\).

Condition (4.67) follows in a similar fashion; see, e.g., (4.78). The preceding discussion leads to the following theorem.
Theorem 4.6 Let \((u, \lambda)\) and \((u_N, \lambda_h)\) be the solutions to (4.59) and (4.64), respectively and suppose (4.13) and (4.14) hold. Then, if \(\lambda \in H^{k+1}(\Omega B)\), there exists \(C \in \mathbb{R}^+\) independent of \(N\) and \(h\) such that
\[
\|u - u_N\|_{1, \Omega} + \|\lambda - \lambda_h\|_{-1/2, \Omega B} \leq C \left\{ \sqrt{N} a_N + h^{k+1} \right\}
\]
where \(a \in (0, 1)\) and \(h\) is given by (4.62).

Proof: From Theorem 4.5 we have
\[
\|u - u_N\|_{1, \Omega} + \|\lambda - \lambda_h\|_{-1/2, \Omega B} \leq C \left\{ \inf_{v \in V_N} \|u - v\|_{1, \Omega} + \inf_{\eta \in \Lambda_h} \|\lambda - \eta\|_{-1/2, \Omega B} \right\}.
\]
Now,
\[
\inf_{v \in V_N} \|u - v\|_{1, \Omega} \leq \|u - \overline{u}_N\|_{1, \Omega} = \|r_N\|_{1, \Omega}
\]
with \(\overline{u}_N, r_N\) given by (4.11) and (4.12), respectively. Using (4.13) and (4.14), we get
\[
\inf_{v \in V_N} \|u - v\|_{1, \Omega} \leq C \sqrt{N} a_N \tag{4.82}
\]
with \(C \in \mathbb{R}^+\) independent of \(N\).

Next, let \(\lambda_I \in \Lambda_h\) be the \(k\th\)-order interpolant of \(\lambda\). Then, since \(\lambda \in H^{k+1}(\Omega B)\), we have
\[
\inf_{\eta \in \Lambda_h} \|\lambda - \eta\|_{-1/2, \Omega B} \leq \|\lambda - \lambda_I\|_{-1/2, \Omega B} \leq C \|\lambda - \lambda_I\|_0, \Omega B \leq C h^{k+1}
\]
which along with (4.82) gives the desired result.

Based on the above theorem, one may obtain the optimal matching between \(N\) and \(h\), i.e., the relationship between the number of singular functions and the number of Lagrange multipliers used in the method, by choosing \(h^{k+1} \sim \sqrt{N} a_N\). This leads to the following approximate expression for \(N\):
\[
N \approx (k + 1) \left| \frac{\ln h}{\ln a} \right|. \tag{4.83}
\]
5 Numerical Results and Discussion

In this section, new numerical results for the Motz problem (3.1)–(3.4) obtained using the Penalty, Hybrid, and Penalty/Hybrid BAMs are presented and discussed in connection with the error analyses of Section 4. Comparisons are also made with the results obtained in [6] with the BAM with Lagrange multipliers.

Obtaining accurate estimates of the leading singular coefficients, \( a_i \), is the main goal of all these special methods. Tables 1–3 list the singular coefficients \( a_i^{35}, i = 1, ..., 35 \), obtained using the Penalty, Hybrid, and Penalty/Hybrid BAMs, respectively (with \( N=35 \)). For comparison purposes, we list in Table 4 the most accurate singular coefficients calculated by the BAM with Lagrange multipliers in [6], using a much larger number of singular functions, i.e., \( N=75 \), and 33 discrete Lagrange multipliers, i.e., \( N_\lambda=33 \). Note that, in this method, \( N \) should be much greater than \( N_\lambda \) in order to obtain satisfactory convergence of the leading singular coefficients. In Table 5, we list the numbers of the converged significant digits of the leading 19 singular coefficients for all four methods, as calculated by Li and Lu [10], using the Conformal Transformation Method (CTM) of Whiteman and Papamichael [20]. We observe that the four BAMs yield very accurate estimates of the singular coefficients. For \( i = 1, 2, 3 \), the Penalty BAM gives one less significant digit than the other three BAMs, while for the higher coefficients all methods yield about the same number of converged significant digits. The BAM with Lagrange multipliers has a slight advantage as \( i \) increases, but it should be kept in mind that the number of singular functions is much higher (\( N=75 \) instead of 35). Moreover, the implementation of the method is more difficult.

In addition to the convergence of the singular coefficients, we have also investigated the effect of the number \( N \) of the singular functions on the error

\[
\epsilon = u - u_N ,
\]

where \( u \) corresponds to a reference solution calculated using the extremely accurate results in [10] and \( u_N \) denotes the approximate solution, and on the condition number of the matrix associated with the linear system arising from each method. The following error norms have been considered:

\[
|\epsilon|_0,\Omega \doteq \left\{ \int_\Omega (u - u_N)^2 ds \right\}^{1/2} , \quad (5.1)
\]
\[ |\epsilon|_{1,\Omega} \equiv \left\{ \int_{\Omega} |\nabla (u - u_N)|^2 ds \right\}^{1/2} = \int_{\Gamma_*} \left\{ (u - u_N) \frac{\partial (u - u_N)}{\partial n} d\ell \right\}^{1/2} \] (5.2)

\[ |\epsilon|_{\infty, AB} \equiv \max_{AB} |\epsilon|, \] (5.3)

\[ |\partial \epsilon|_{\infty, BC} \equiv \max_{BC} |\partial \epsilon|, \] (5.4)

\[ |\partial \epsilon|_{\infty, CD} \equiv \max_{CD} |\partial \epsilon|, \] (5.5)

<table>
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<tr>
<th>(i)</th>
<th>(a_i^N)</th>
<th>(i)</th>
<th>(a_i^N)</th>
</tr>
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Table 1
Computed singular coefficients with the Penalty BAM for \(N = 35\).

For the computations with the Penalty/ Hybrid BAM, we choose \(c = 1\) and \(w^2 = c^*(N + 1)\) with \(c^* = 1\); (cf. (4.46) and the discussion at the end of Section 4.3). The matrix \(A_{PH} \in \mathbb{R}^{N \times N}\) of the linear system that arises from (4.27), is symmetric and positive definite (provided (4.46) holds), and its condition
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Table 2
Computed singular coefficients with the Hybrid BAM for $N = 35$.

number, $\kappa$, is given as the ratio of the maximum to the minimum eigenvalue:

$$
\kappa(A_{PH}) = \frac{\lambda_{\text{max}}(A_{PH})}{\lambda_{\text{min}}(A_{PH})}, \quad (5.6)
$$

In the Hybrid BAM, the matrix $A_H \in \mathbb{R}^{N \times N}$ of the linear system arising from (4.22) is positive definite, but not symmetric. Hence, the condition number is calculated as follows:

$$
\kappa(A_H) = \frac{\sqrt{\lambda_{\text{max}}(A_H^T A_H)}}{\sqrt{\lambda_{\text{min}}(A_H^T A_H)}}, \quad (5.7)
$$

As described in [8], in the Penalty BAM, the side $\overline{AB}$ is divided into $M$
<table>
<thead>
<tr>
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<th>$a_i^N$</th>
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Table 3
Computed singular coefficients with the Penalty/Hybrid BAM for $N = 35$.

equally spaced pieces of width $h = 1/M$. The direct collocation method is used to impose the boundary conditions (3.2)–(3.3). The condition number of the matrix $F \in \mathbb{R}^{(4M) \times (N+1)}$ of the resulting linear system is given by (5.7), with $F$ replacing $A_H$. Note that since $4M >> N+1$, the least squares method is used to solve the linear system.

The variations of the error norms (5.1)–(5.5) with $N$, as well as the condition numbers obtained using the Penalty, the Hybrid, and the Penalty/Hybrid BAMs, are tabulated in Table 6. These are presented graphically in Figure 2, where the exponential convergence rates established in Section 4 are readily visible. Upon careful examination of the numbers given in Table 6, we see that for the Penalty BAM we have

$$|u - u_N|_{\infty,AB} \rightarrow 2.8 \times 0.55^N, \quad |\epsilon|_{0,\Omega} \rightarrow 5.0 \times 0.57^N, \quad |\epsilon|_{1,\Omega} \rightarrow 19.5 \times 0.58^N,$$
\[
\begin{array}{|c|c|c|}
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i & a_i^N & i & a_i^N \\
\hline
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2 & .876559201950877 \times 10^2 & 20 & -.529575461575406 \times 10^{-5} \\
3 & .172379150794469 \times 10^2 & 21 & .229103011774740 \times 10^{-5} \\
4 & -.807121525969814 \times 10^1 & 22 & .1063419634823553 \times 10^{-5} \\
5 & .144027271702291 \times 10^1 & 23 & .531399419800137 \times 10^{-6} \\
6 & .331054885920656 \times 10^0 & 24 & -.2474206450164 \times 10^{-6} \\
7 & .275437344509193 \times 10^0 & 25 & .108706636458335 \times 10^{-6} \\
8 & -.869329945252286 \times 10^{-1} & 26 & .529296106984506 \times 10^{-7} \\
9 & .336048784263123 \times 10^{-1} & 27 & .264253479339111 \times 10^{-7} \\
10 & .153843744820525 \times 10^{-1} & 28 & -.120550254504250 \times 10^{-7} \\
11 & .730230167439347 \times 10^{-2} & 29 & .116026519978975 \times 10^{-8} \\
12 & -.3184113958881 \times 10^{-2} & 30 & .6227639522802 \times 10^{-8} \\
13 & .122064610749685 \times 10^{-2} & 31 & .332311983973516 \times 10^{-8} \\
14 & .530965479850461 \times 10^{-3} & 32 & .554937941399033 \times 10^{-9} \\
15 & .271512187507913 \times 10^{-3} & 33 & -.107137722721491 \times 10^{-7} \\
16 & -.120046373993572 \times 10^{-3} & 34 & .719736757310813 \times 10^{-8} \\
17 & .505398053367447 \times 10^{-4} & 35 & .432710661454326 \times 10^{-8} \\
18 & .231668535028465 \times 10^{-4} & 36 & .405044840445786 \times 10^{-8} \\
\hline
\end{array}
\]

Table 4
Computed singular coefficients with the BAM with Lagrange multipliers [6] for
\(N=75\) and \(N_x=33\) (only the first 36 coefficients are listed).

while for the Hybrid BAM

\[
|u - u_N|_{\infty,AB} \to 3.5 \times 0.55^N, \quad |\epsilon|_{0,\Omega} \to 4.9 \times 0.57^N, \quad |\epsilon|_{1,\Omega} \to 3.5 \times 0.59^N,
\]

and for the Penalty/Hybrid BAM,

\[
|u - u_N|_{\infty,AB} \to 6.7 \times 0.54^N, \quad |\epsilon|_{0,\Omega} \to 5.8 \times 0.56^N, \quad |\epsilon|_{1,\Omega} \to 5.1 \times 0.61^N.
\]

It appears that the Penalty BAM slightly outperforms the other two, when
the errors (5.1)-(5.5) are of interest.
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Table 5
Numbers of converged significant digits in \(a_i^N\), \(i = 1, ..., 19\) for the four methods under study.

As for the condition numbers, we have

\[
\kappa(F) \to 0.09 \times 1.60^N, \quad \kappa(A_H) \to 0.7 \times 1.99^N, \quad \kappa(A_{PH}) \to 1.1 \times 1.99^N.
\]

Therefore, the condition number for the Penalty BAM grows at a significantly slower rate than those of the other two BAMs, which is also evident in Figure 2. Hence, in terms of numerical stability, the Penalty BAM is to be preferred.

In summary, when compared to the Penalty BAM, the Hybrid and the Penalty/Hybrid BAMs may yield slightly more accurate estimates for the singular co-
Table 6
Error norms and condition numbers for the Penalty, the Hybrid, and the Penalty Hybrid BAMs for different values of $N$.

Efficients, but their performance is slightly worse in terms of the error norms (5.1)–(5.5), due to the ill-conditioning of the matrices associated with the corresponding linear systems.

Finally, we wish to make a short remark on the choice $N = 35$ in our numerical experiments. Take, for example, the Hybrid BAM for which we have $|\epsilon|_{1,\Omega} \approx (|\epsilon|^2_{0,\Omega} + |\epsilon|^2_{1,\Omega})^{1/2} = 0.211 \times 10^{-6}$ (see Table 6). Since the true solution satisfies $|u|_{1,\Omega} = O(10^{-4})$, the relative errors in the $H^1$ norm reach $O(10^{-9})$, whereas the condition number reaches $O(10^{10})$! It is clear that 16-decimal-digit accuracy allowed by the double-precision arithmetic is reached when $N=35$. For $N > 35$, the increasing condition number causes a loss of accuracy.

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Fig. 2. Convergence and variation of the condition numbers with $N$ when using the Penalty, the Hybrid, and the Penalty Hybrid BAMS. The error estimates are defined by (5.1)-(5.5)
References


