

# Initial Value Problems of ODEs

# Differential Equations

**Objective:** Solve an equation containing an unknown function and one or more of its derivatives

**Problem:** Find  $y(t)$  satisfying:

$$y'(t) = f(t, y(t)), \quad t \geq t_0 \quad (1)$$

$$y(t_0) = y_0 \quad (2)$$

- (1)–(2) is called an initial value problem of the ODE  $y'(t) = f(t, y)$ .
- $y(t)$  is a scalar valued function of  $t$ .

## Examples

$$y'(t) = \sin(t)$$

$$y\left(\frac{\pi}{3}\right) = 2$$

- $y'(t) = \sin(t) \implies y(t) = -\cos(t) + C$  (general solution)

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- $y'(t) = \sin(t) \implies y(t) = -\cos(t) + C$  (general solution)
- Using initial condition  $y\left(\frac{\pi}{3}\right) = 2$ , we have a particular solution by solving for  $C$

$$y(t) = 2.5 - \cos(t)$$

## Examples

$$y'(t) = \lambda y(t) + b(t), \quad t \geq t_0 \text{ and } \lambda \text{ constant}$$

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Solve using the method of **integrating factors!**

$$\begin{aligned}y'(t) - \lambda y(t) &= b(t) \\(y'(t) - \lambda y(t))e^{-\lambda t} &= e^{-\lambda t} b(t)\end{aligned}$$

Recognize that  $(y'(t) - \lambda y(t))e^{\lambda t} = \frac{d}{dt}(y(t)e^{-\lambda t})$  then

$$\frac{d}{dt}(y(t)e^{-\lambda t}) = e^{-\lambda t} b(t)$$

## Examples

$$\frac{d}{dt}(y(t)e^{-\lambda t}) = e^{-\lambda t}b(t)$$

Integrating both sides:

$$e^{-\lambda t}y(t) = \int_{t_0}^t e^{-\lambda s}b(s) ds + C$$

so the general solution is

$$y(t) = e^{\lambda t} \left[ C + \int_{t_0}^t e^{-\lambda s} b(s) ds \right] = Ce^{\lambda t} + \int_{t_0}^t e^{\lambda(t-s)} b(s) ds$$

## Second order IVP (Hooke's Law - spring-mass oscillation)

If the displacement is not too large, the force exerted on the mass is proportional to the displacement from the origin

$$\begin{aligned}y''(t) &= -ky, \quad k > 0 \\y(0) &= y_0 \\y'(0) &= 0\end{aligned}$$

- $y(t) = c_1 \sin(\sqrt{kt}) + c_2 \cos(\sqrt{kt})$



## Euler's method

$$\begin{aligned}y'(t) &= f(t, y(t)), \\ y(a) &= y_0 \quad a \leq t \leq b\end{aligned}$$

- **Step 1:** Divide  $[a, b]$  into  $N$  subintervals of size  $h = \frac{b - a}{N}$

$$a = t_0 < t_1 < \cdots < t_{N-1} < t_N = b$$

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- **Step 2:** Replace  $y'(t)$  by an approximation (from calc I)

$$y'(t) = \lim_{h \rightarrow 0} \frac{y(t+h) - y(t)}{h}$$

so starting with  $[t_0, t_1]$ ,

$$y'(t_0) \approx \frac{y(t_1) - y(t_0)}{h} = f(t_0, y_0)$$

## Euler's method for $y'(t) = f(t, y(t))$ $a \leq t \leq b$

**t grid:**  $a = t_0 < t_1 < \cdots < t_{N-1} < t_N = b$

- On subinterval  $[t_0, t_1]$ : replace  $y'(t_0)$  by a finite difference:

$$y'(t_0) \approx \frac{y(t_1) - y(t_0)}{h} = f(t_0, y_0) \implies y_1 = y_0 + hf(t_0, y_0)$$

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- On subinterval  $[t_1, t_2]$ : replace  $y'(t_1)$  by a finite difference:

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In general on subinterval  $[t_k, t_{k+1}]$ : replace  $y'(t_k)$  by a finite:

$$y'(t_k) \approx \frac{y(t_{k+1}) - y(t_k)}{h} = f(t_k, y_k) \implies y_{k+1} = y_k + hf(t_k, y_k)$$

## Euler's method - quick derivation



Brook Taylor (1685–1731)<sup>1</sup>

### Theorem (Taylor)

*Let  $f, f', \dots, f^{(n)}$  be continuous on  $[a, b]$  and let  $f^{(n+1)}$  exist for all  $t$  in  $(a, b)$ . Then there is a number  $\xi$  between  $t$  and  $a$  such that*

$$f(t) = f(a) + (t - a)f'(a) + \frac{(t - a)^2}{2!}f''(a) + \dots + \frac{(t - a)^n}{n!}f^{(n)}(a) + \frac{(t - a)^{n+1}}{(n + 1)!}f^{(n+1)}(\xi)$$

<sup>1</sup><http://www-history.mcs.st-andrews.ac.uk/PictDisplay/Taylor.html>

## Euler's method - quick derivation



Leonard Euler (1707–1783)<sup>2</sup>

$$y_{k+1} = y_k + hf(x_k, y_k)$$

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# Euler's method - quick derivation

## Taylor's Theorem

Given the (IVP)  $y'(t) = f(t, y(t))$ , expand  $y(t)$  about  $t_k$  as

$$y(t) = y(t_k) + (t - t_k)y'(t_k) + \frac{(t - t_k)^2}{2}y''(\xi_k), \quad \xi_k \in [t_k, t_{k+1}]$$



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Evaluating at  $t = t_{k+1}$  and recalling that  $h = t_{k+1} - t_k$  yields:

$$y(t_{k+1}) = y(t_k) + hf(t_k, y(t_k)) + \frac{h^2}{2}y''(\xi_k)$$

Dropping the error term  $\frac{h^2}{2}y''(\xi_k)$


$$y_{k+1} = y_k + hf(t_k, y_k), \quad k = 0, 1, 2, \dots$$

## Euler's method - works well in some cases



Leonard Euler (1707–1783)<sup>3</sup>

$$y_{k+1} = y_k + hf(x_k, y_k)$$

Euler's method is simple and works for some problems BUT is prone to errors and can be unstable for *stiff problems* (MA 428)  [Hidden Figures]

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# Euler's method - modeling the spread of an infection

**Modeling the spread of an epidemic** (Kermack & McKendrick, *Proc Roy, Soc.* (1927))

## Assumptions

- Population divided into **healthy individuals** (H), **infected individuals** (I) and the **dead** (D)

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## Assumptions

- Population divided into **healthy individuals** (H), **infected individuals** (I) and the **dead** (D)
- The epidemic spreads so quickly that changes in population due to birth, death or migration can be ignored.
- The disease is transmitted to healthy individuals at a rate proportional to the product of **healthy** and **infected** people

## Euler's method for systems - modeling the spread of an infection

- Turning our assumptions into equations:

$$\frac{dH}{dt} = -cHI, \quad \frac{dI}{dt} = cHI - mI, \quad \frac{dD}{dt} = mI$$

where  $c$  is the **transmission rate** and  $m$  is the **mortality** rate of infected individuals.

- The model can be reduced to a single equation. First divide the H equation by the D equation to get

$$\frac{dH}{dD} = -\frac{c}{m}H$$

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whose solution is:

$$H = H_0 e^{-\frac{c}{m}D}$$

where  $H_0$  is the number of healthy individuals.



## Euler's method - modeling the spread of an infection

- If  $N$  is the size of the population then

$$H + I + D = N \implies I = N - H - D$$

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$$\frac{dD}{dt} = mI \implies \frac{dD}{dt} = m(N - H - D) \implies \boxed{\frac{dD}{dt} = m[N - H_0 e^{-\frac{c}{m}D} - D]}$$

- Once  $D$  is determined, we can solve for  $H$  and  $I$  using

$$\boxed{H = H_0 e^{-\frac{c}{m}D}}$$

$$\boxed{I = N - H - D}$$

## Exercise

Write a function

`[t_vals, y_vals] = approx_ode(f,a,b,initial_value,n)` that takes as input a function defined in a file `yprime = f(t,y)`, defined in `f.m` and two values `a` and `b` indicating the left and right intervals on which the initial value problem is defined and `n`, the number of Euler steps. Your function should return 2 vectors (`t_vals` contains the values  $t_0, t_1, \dots, t_N$  and `y_vals` is the solution at those points  $y_0, y_1, \dots, y_N$ ) Test your code on the initial value problem

$$\frac{dy}{dt} = 1 + \frac{y}{t} \quad 1 \leq t \leq 6, \quad y(1) = 1$$

whose exact solution is  $y(t) = t(1 + \ln t)$ .